

WEST Search History

DATE: Saturday, March 21, 2009

Hide?	<u>Set Name</u>	<u>Query</u>	<u>Hit Count</u>
		<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>	
<input type="checkbox"/>	L44	ground and contact and L42	26
<input type="checkbox"/>	L43	groung and contact and L42	0
<input type="checkbox"/>	L42	sensor and L41	34
<input type="checkbox"/>	L41	axis and L40	34
<input type="checkbox"/>	L40	soles and L39	34
<input type="checkbox"/>	L39	foot and L38	39
<input type="checkbox"/>	L38	L37 and coordinate	39
<input type="checkbox"/>	L37	position and orientation and L36	44
<input type="checkbox"/>	L36	(L8 or L9) and L35	85
<input type="checkbox"/>	L35	landed and landing and foot and robot\$6	153
<input type="checkbox"/>	L34	landed and landing and foot and footstep and robot\$6	6
<input type="checkbox"/>	L33	landed and landing and foot and footstep and (L8 or L9)	3
<input type="checkbox"/>	L32	landded and landing and foot and footstep and (L8 or L9)	0
<input type="checkbox"/>	L31	landded and landing and foot and footstep and L22	0
<input type="checkbox"/>	L30	landded and landing and foot and L29	0
<input type="checkbox"/>	L29	posture and L28	52
<input type="checkbox"/>	L28	gravity and coordinate and L27	53
<input type="checkbox"/>	L27	estimat\$3 and position and L26	62
<input type="checkbox"/>	L26	dynamics same model and L23	74
<input type="checkbox"/>	L25	dyanamics and L23	0
<input type="checkbox"/>	L24	dyanamics same model and L23	0
<input type="checkbox"/>	L23	L21 and L22	184
<input type="checkbox"/>	L22	movement or trajectory and L21	2693185

<input type="checkbox"/>	L21	floor and zmp and L8	193
<input type="checkbox"/>	L20	floor and zmp and L19	0
<input type="checkbox"/>	L19	(5024920 5173382 5490103 5557564 5901829 6201488 6521838 6518503 6695663 6592418 5733819 6027554 6663326 6694847 6685863 4252414 4588518 4561746 4719331 5118090 5434926 5419740 5558196 5527940 5716481).pn.	47
<input type="checkbox"/>	L18	motion pattern and L16	2
<input type="checkbox"/>	L17	motion pattern and stor\$3 and L16	0
<input type="checkbox"/>	L16	freedom and L15	5
<input type="checkbox"/>	L15	L13 and L14	6
<input type="checkbox"/>	L14	L13 and gait or gate	1272919
<input type="checkbox"/>	L13	('6580969' 'l'6493606' 'l'6463356' 'l'6289265' 'l'6243623' 'l'5872893' 'l'5841258' 'l'5838130' 'l'5594644' 'l'EP 1136193A' 'l'EP 1103451A')!.ABPN1, NRPN,PN,TBAN,WKU.	18
<input type="checkbox"/>	L12	('20030019671' 'l'20020138359' 'l'6591923' 'l'6458011')!.ABPN1,NRPN,PN, TBAN,WKU.	7
<input type="checkbox"/>	L11	(legged robot or pet robot or humanoid near10 robot) motion and pattern	13
<input type="checkbox"/>	L10	(legged robot or pet robot or humanoid near10 robot) motion and pattern and L9	0
<input type="checkbox"/>	L9	(6252544 6493606 6243623 6289265 5673367 5355064 5455497 5325031 5357433 5594644 6580969 6718231 5504841 5842533 4621333 4633059 4987527 5937398 6064168 6429812 6584377 5259064 5349646 5946041 4540211 4762261 5273296 5616917 5627440 5794621 6059092 6059092 6068201 6456728 6505098 6711469 5402050 5525883 5841258 6463356 4614504 5040626 5343397 5369346 5378969 5644204 5672924 5838130 5872893 6229552).pn.	97
<input type="checkbox"/>	L8	(700/245 700/246 700/251 700/253 700/260 700/261 or 318/568.1 318/568.12 318/568.16 318/568.17 318/568.2 or 901/1 901/9 901/46 or 180/8.1 180/8.6 180/65.1 or 701/23 or 320/116 320/120 or 446/376 446/384).ccls.	10678
<input type="checkbox"/>	L7	6580969.pn.	2
<input type="checkbox"/>	L6	11/456454	2
<input type="checkbox"/>	L5	10/511608	1
<input type="checkbox"/>	L4	coordinate and L3	7
<input type="checkbox"/>	L3	"foot-sole" and L1	22

<input type="checkbox"/>	L2	"based on" and L1	47
<input type="checkbox"/>	L1	foot same position same sole	4880

END OF SEARCH HISTORY